

Radar Remote Sensing of the Meteo-Marine Parameters in the Baltic Sea

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Motivation

- **To develop/improve, validate and demonstrate the value of meteo-marine parameters derived from different radar data**
 - Assess current state-of-the-art methods in estimating meteo-marine parameters
 - High resolution TerraSAR-X/TanDEM-X StripMap imagery
 - Medium resolution Sentinel-1A/B IW swath imagery
 - Marine radar imagery
 - Validate wave retrieval methods in the Baltic Sea
 - XWAVE_C
 - Pleskachevsky et al. 2016, *ISPRS*, 119; Rikka et al. 2018, *IJRS*, 39(4)
 - CWAVE_S1-IW
 - Pleskachevsky et al. (*submitted to IJRS*); Rikka et al. 2018, *Remote Sensing*, 10(5)
 - Method for marine radar
 - Rikka et al. (*submitted to IEEE Geoscience and Remote Sensing Letters*)
 - Validate wind retrieval methods (XMOD-2 and CMOD)
 - Rikka et al. 2018, *IJRS*, 39(4); Rikka et al. 2018, *Remote Sensing*, 10(5)
- to compare different radar (TS-X, Sentinel-1, marine radar) wave retrievals with (operational) wave model results
- to examine the added benefits of radar data to maritime situation awareness in the Baltic Sea

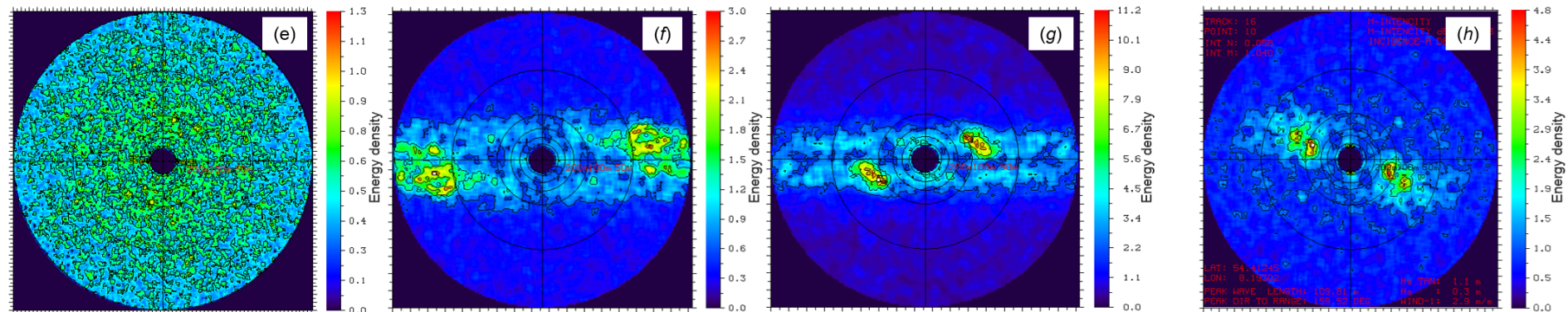
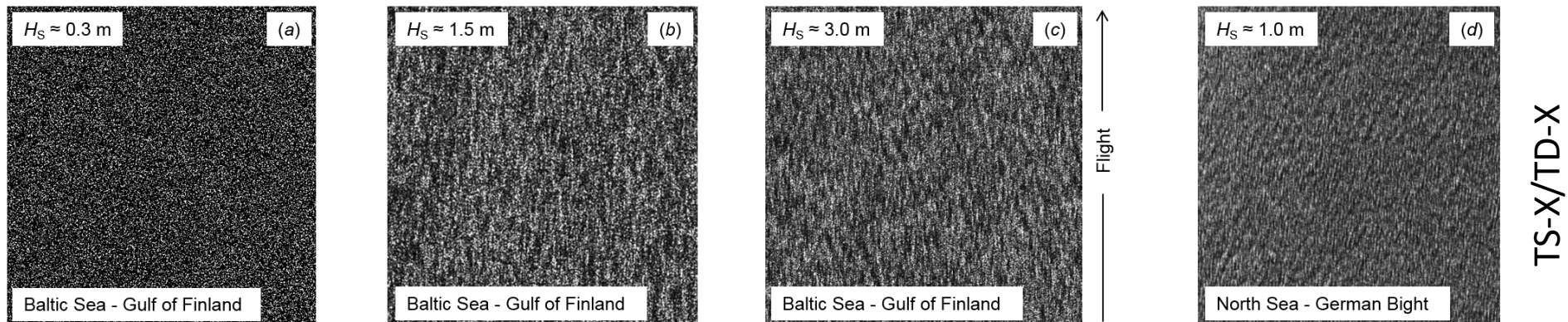
Meteo-marine climate in the Baltic Sea

- Complex coastline
- Thousands of islands
- Dominant wind direction
 - Sector $180^\circ - 315^\circ$ (S – NW)
 - Frequently observed slanting fetch cases, up to 50°
- Dominant wave period
 - 2 – 8 s
 - Small swell component in H_S
- Dominant wave height
 - H_S between 0–3 m
 - Up to about 10 m observed
 - Dependent of the region
 - Clear annual cycle
- Short wave „memory“
- **Hardly recognizable wave pattern on SAR imagery**
- **Noisy SAR images**



Leppäranta and Myrberg, 2009

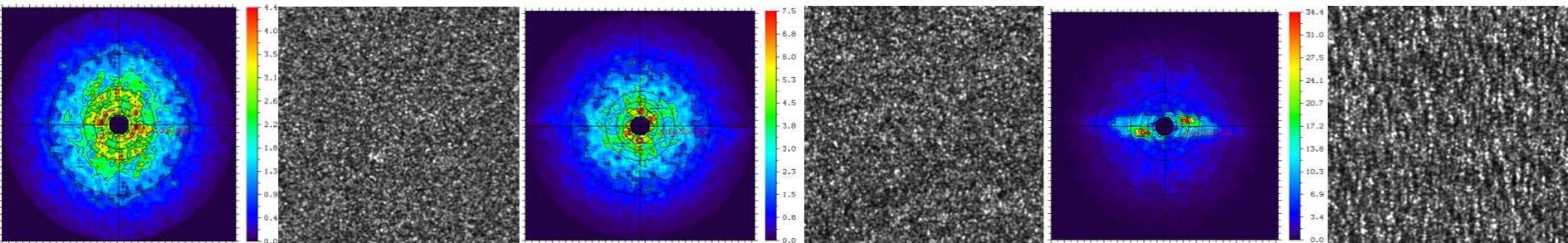
Radar imaging of sea surface: SAR



2015.07.05 04:59 UTC – H_s 0.5 m

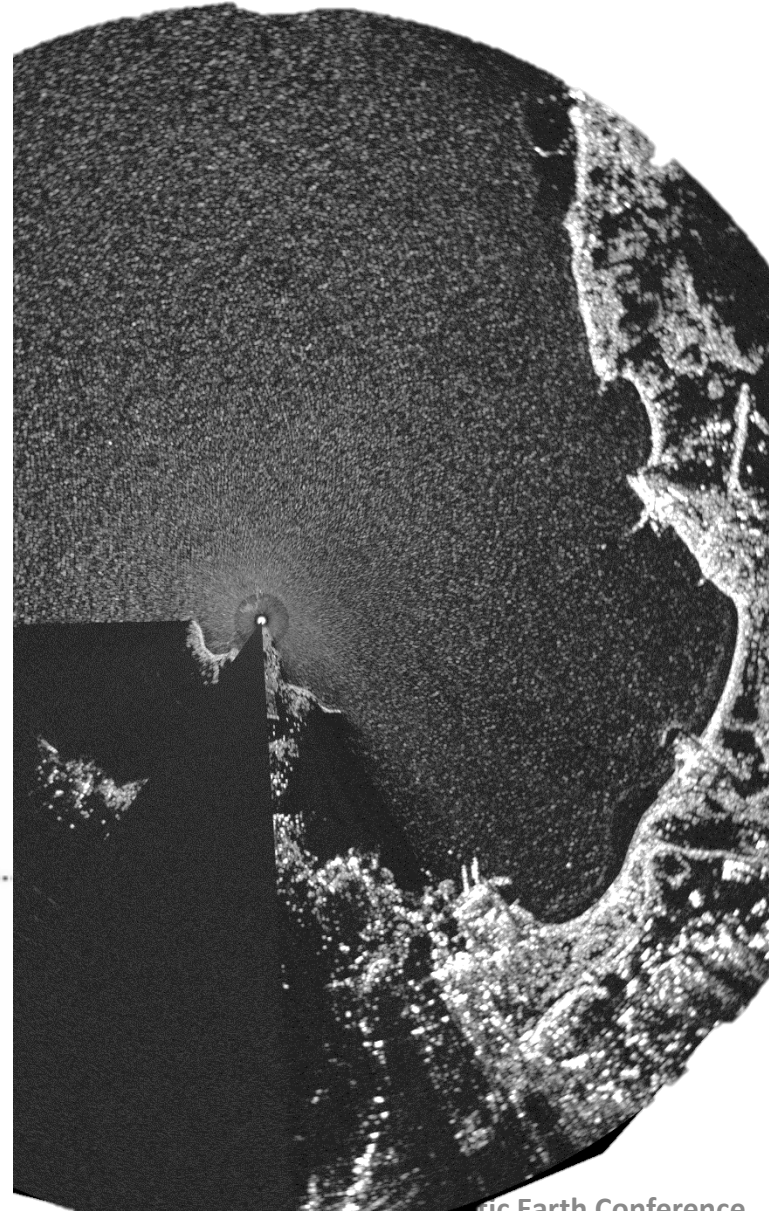
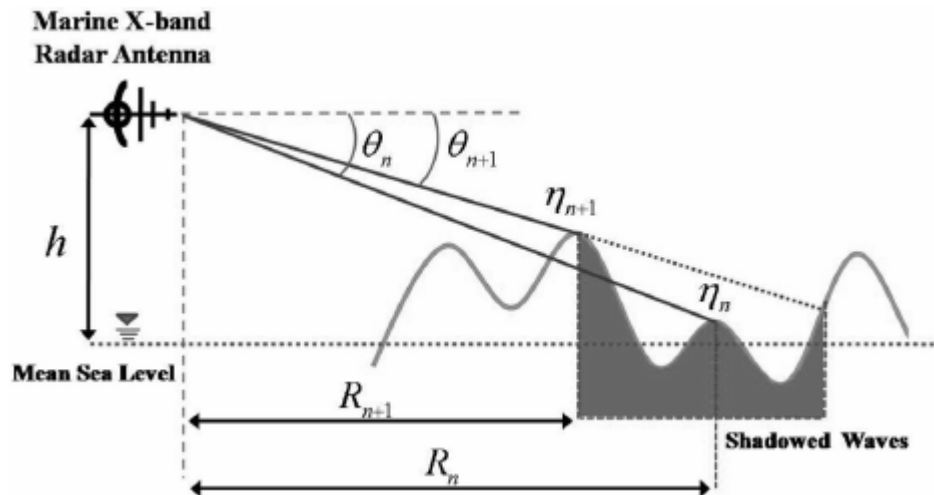
2015.10.01 16:22 UTC – H_s 2.7 m

2015.01.11 16:19 UTC – H_s 3.9 m



Radar imaging of sea surface: marine radar

- Marine radar imaging introduce additional effects
 - Very high incidence angles
 - **Shadowing**
 - Scattering from micro breakers, i.e. whitecapping



Data – *in situ* measurements, radar, wave model

Dev. – algorithm development; Val. – validation; Comp. – comparison with *in situ* or wave model results; Stat. – seasonal or regional statistics

Sensor	Radar wavelength	Pixel size	Temp. res.	Spatial coverage	Period	No. of images	Purpose	<i>In situ</i> collocations	Wave model collocations
TS-X TD-X	X-band 3.1 cm	3×3 m	On demand	30× up to about 250 km	2012-2017	92	Dev. Val. Comp.	117 H_S 102 U_{10} 44 L_P , γ_P	55 L_P , γ_P SWAN
Sentinel-1 IW	C-band 5.5 cm	10×10 m	1 – 2 days	250× up to about few 10^3 km	2015-2016	15 460	Val. Comp. Stat.	52 H_S 358 U_{10} 101 H_S	49314 H_S WAM 201 H_S
Marine radar	X-band 3.2 cm	5×5 m	1 h	About 10 km from radar tower	18.10. - 14.11.16	559	Dev. Val.	1678 H_S 1464 H_S	- -

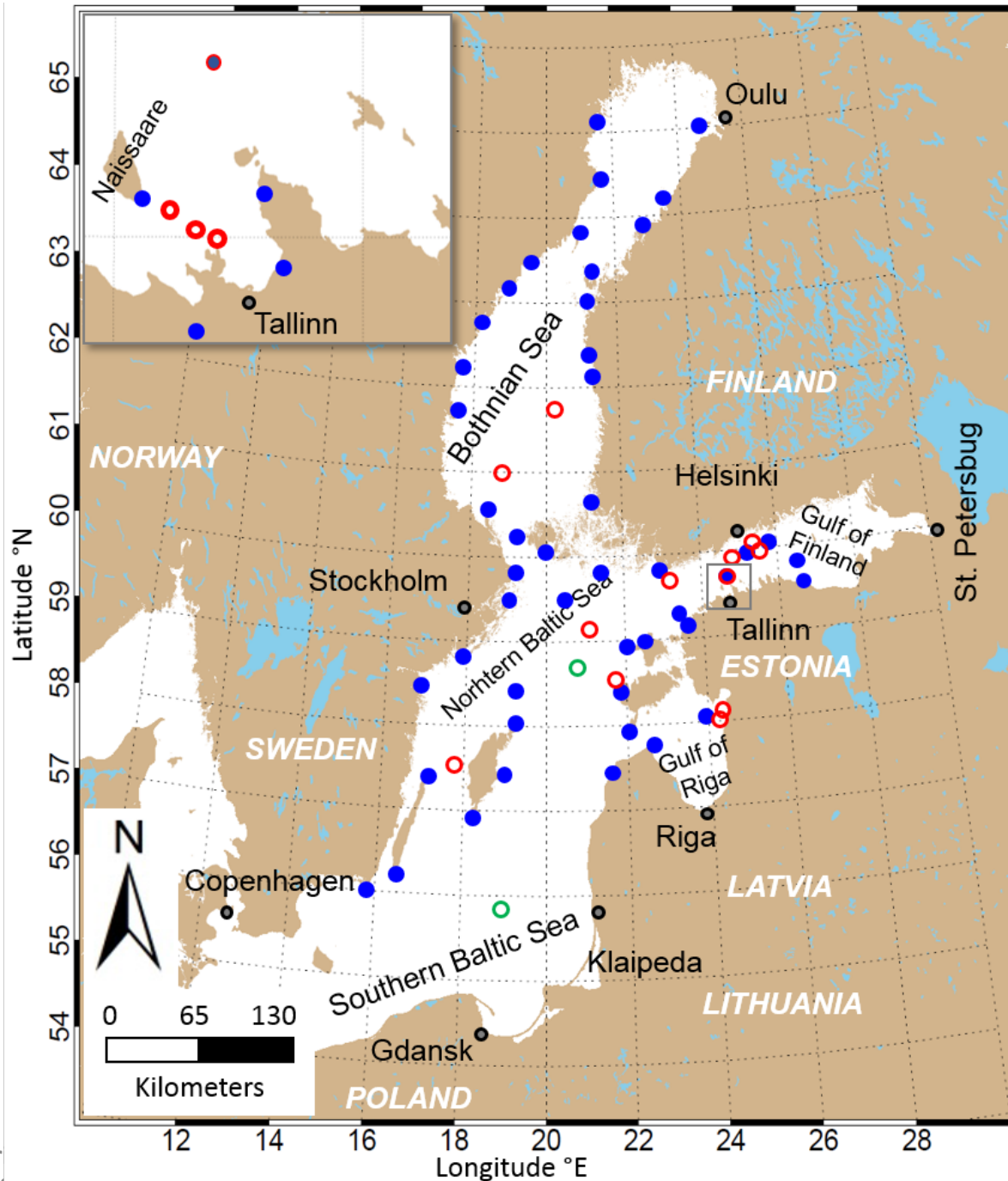
H_S total significant wave height

U_{10} wind speed

L_P peak wave length

γ_P peak wave propagation direction

Data – *in situ* measurements, radar,
wave model



SAR methods: wind

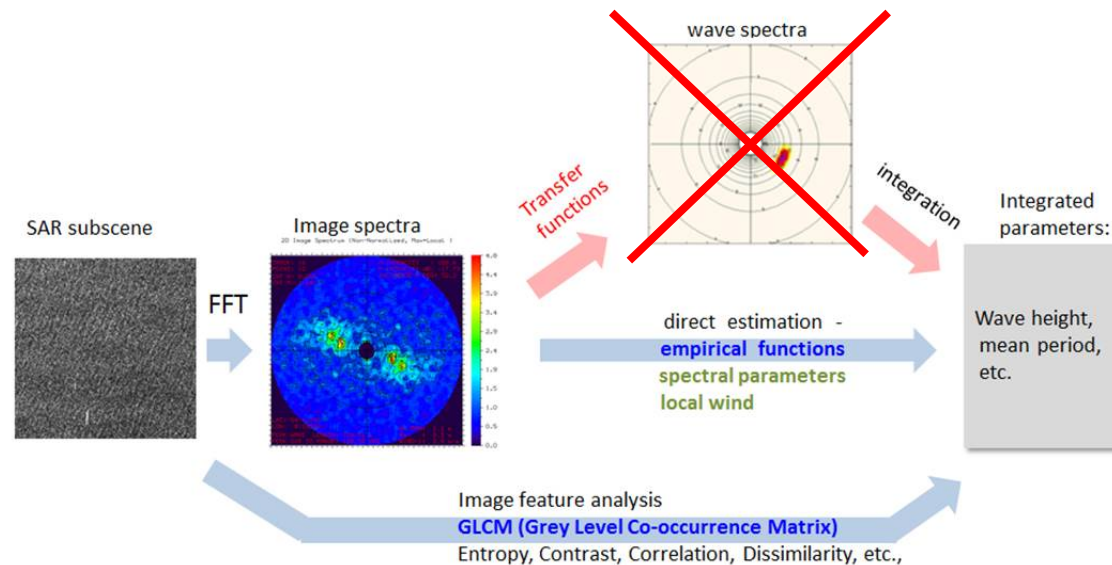
- Sea state is strongly dependent on local wind characteristics
- XMOD-2 and CMOD
- $\sigma_0(U, \theta, \phi) = B_0^p(U_{10}, \theta)(1 + B_1(U_{10}, \theta) \cos(\phi) + B_2(U_{10}, \theta) \cos(2\phi))$
 - σ_0 – Normalized Radar Cross Section (NRCS)
 - U_{10} – wind speed
 - ϕ – wind direction relative to flight direction
 - θ – local incidence angle
 - B_i - tuned function parameters for XMOD-2 and CMOD separately
- With polarisation ratio for XMOD-2 (Li and Lehner, 2014):
 - $PR = \frac{\sigma_0^{VV}}{\sigma_0^{HH}} = X_0 \text{EXP}(X_1 \theta)$, where X_0 and X_1 are tuning coefficients
- According to Monaldo et al. 2016, separate GMFs are used to receive wind speed
 - CMOD4 with Thompson, D. R., et al. (1998) PR for HH polarization and CMOD5.N for VV polarization
- Wind direction from Weather Research and Forecasting Model (WRF) is used (Skamarock et al. 2005)
- WRF wind direction are interpolated to the sea state calculation grid

Radar methods: sea state

- Calculation of NRCS from pixel's digital number
- Artefacts filtering
- Subscene normalization

$$\sigma_n(x, y) = \frac{\sigma_0(x, y) - \langle \sigma_0 \rangle}{\langle \sigma_0 \rangle}$$
- Fast Fourier Transform
- Empirical function without transformation into wave spectra
- Additional Grey Level Co-occurrence Matrix (GLCM) image statistics
- General methods are based on validation data matchups from open source measurement data from all over the World

Sea state parameter estimation



Quality Control: Buoys (location) and Wave model results (spatial distribution)

- XWAVE_C - Pleskachevsky et al. 2016, *ISPRS*, 119
- CWAVE_S1-IW - Pleskachevsky et al. (*submitted to IJRS*)

Radar methods: sea state

- Energy of image spectrum retrieved by FFT operator

- $$E_{IS} = \int_{k_x^{min}}^{k_x^{max}} \int_{k_y^{min}}^{k_y^{max}} IS(k_x, k_y) dk_x dk_y$$
 - $k = \sqrt{k_x^2 + k_y^2}$ where k_{max} and k_{min} depend on radar data used

- Significant wave height

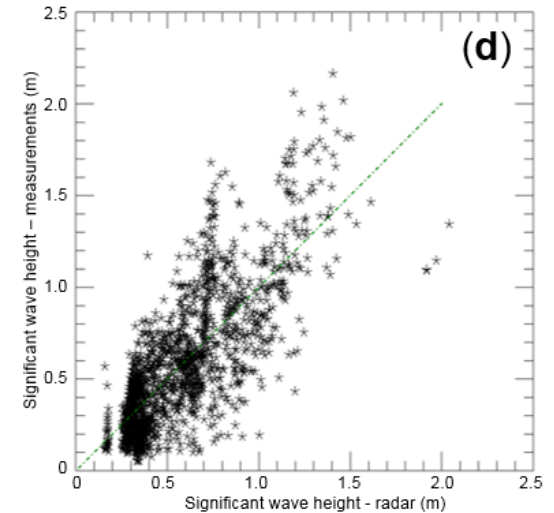
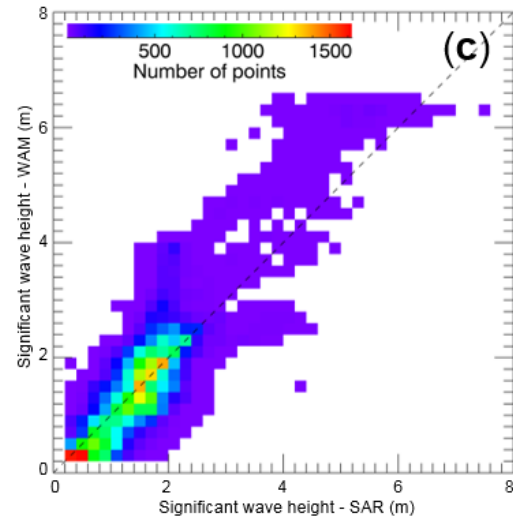
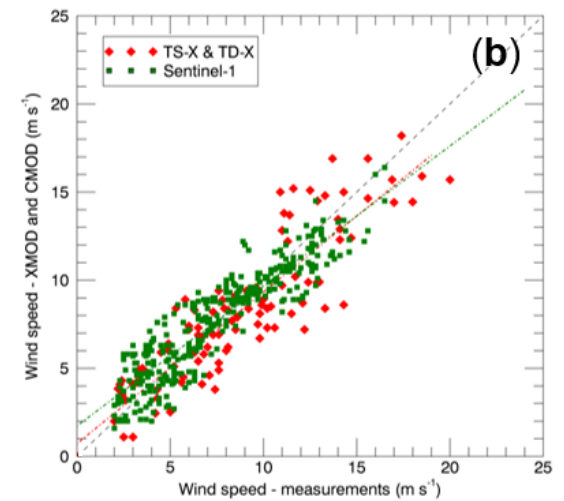
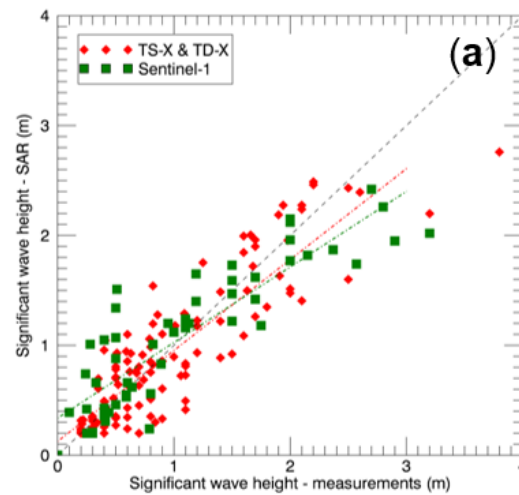
- $$H_S = a_0 \sqrt{B_0 E_{IS} \tan(\theta)} + \sum_{i=1}^n a_i B_i$$
 - θ is local incidence angle
 - a_i are coefficients, and B_i are functions of spectral parameters, wind and GLCM results depending on data/sensor

- Empirical algorithm for marine radar data

- H_S estimation based on image spectra E_{IS}
- Calculated parameters are tested against measured *in situ* values
 - Best-fit trendline technique
 - Pearson correlation coefficient
 - Minimize RMSE
- $B_0 = f(d, \theta)$
- $B_1 = f(d, \theta, \bar{x})$, where $\bar{x} = \sum_{i=0}^{2G-2} i P_{x+y}(i)$
- $B_2 = f(d, \theta, \sigma^2)$, where $\sigma^2 = \sum_{i=0}^{G-1} \sum_{j=0}^{G-1} (i - \mu)^2 P(i, j)$
 - d distance from radar tower
 - \bar{x} GLCM mean
 - σ^2 GLCM variance
 - P number of collocations in GLCM levels G

Results: validation

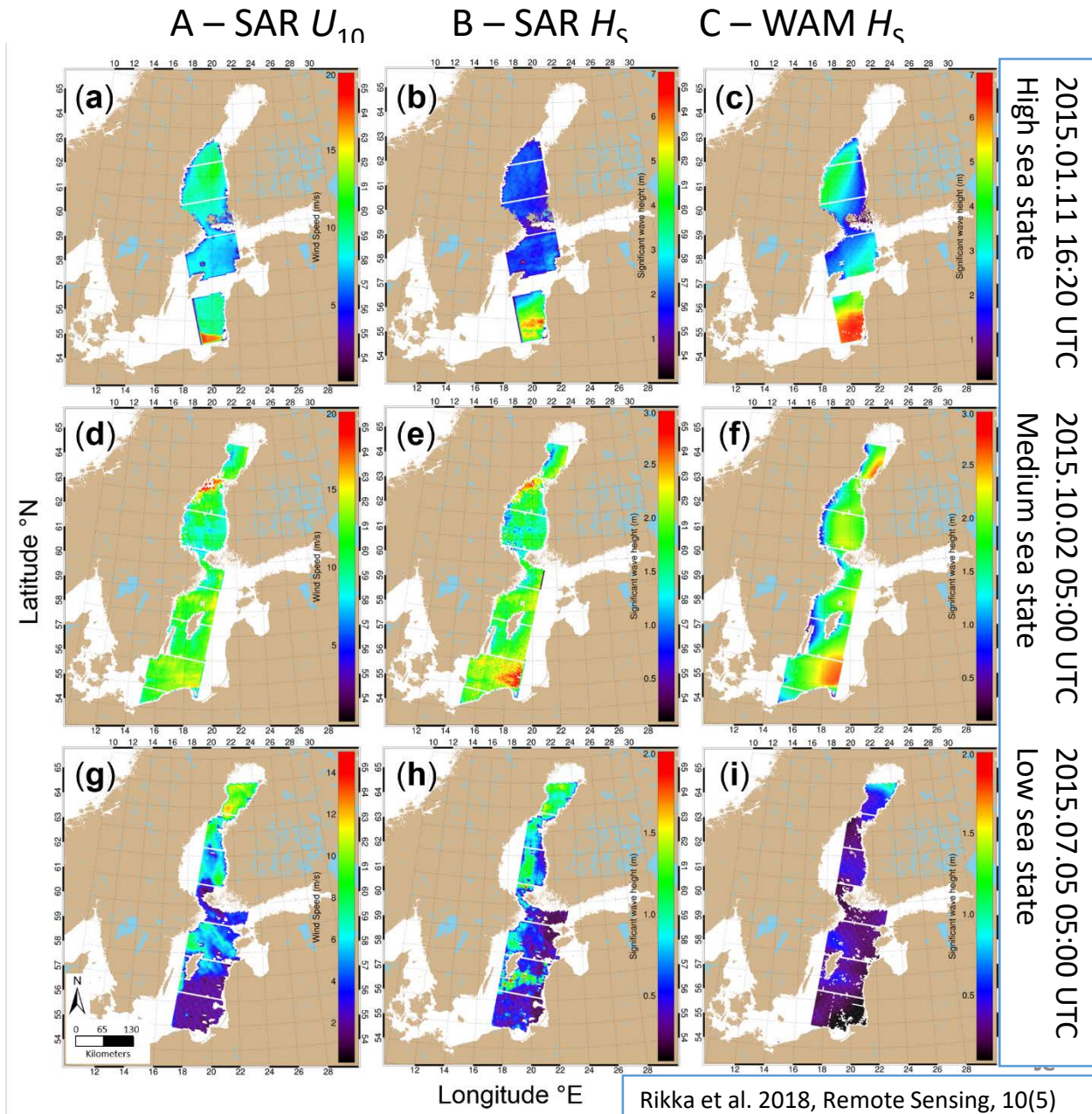
- High agreements between *in situ* wind and radar-derived wind speed, especially for Sentinel-1 results where RMSE less than 1.5 m s^{-1}
- Radar derived H_S accurate, r slightly less than 0.90, RMSE less than 0.5 m
- High agreement in range of 0 – 3 m (typical for Baltic Sea) between SAR and WAM



Collocation pair	TS-X TD-X vs. <i>in situ</i>	TS-X TD-X vs. <i>in situ</i>	Sentinel-1 vs. <i>in situ</i>	Sentinel-1 vs. <i>in situ</i>	Sentinel-1 vs. WAM	Marine radar vs. <i>in situ</i>
Parameter	H_S	U_{10}	H_S	U_{10}	H_S	H_S
r	0.88	0.90	0.88	0.91	0.86	0.78
RMSE	0.32	2.02	0.40	1.43	0.47	0.23
SI	0.33	0.24	0.37	0.19	0.33	0.41
n	117	102	52	357	49314	1678

Sentinel-1 data for regional studies

- Wave height up to 7.5 m
- General agreement in the wave height values and location of maximum
- Storm peak area smaller from SAR data
- Storm does not spread as much to the north as on WAM field
- Maximum H_s higher with SAR-derived results
- Wave field variability (STD) many times larger for SAR dataset
- Variability in wave model fields lost mostly due to wind forcing, **local fine-scale wind field variations and gusts are not included in wave model forcing**



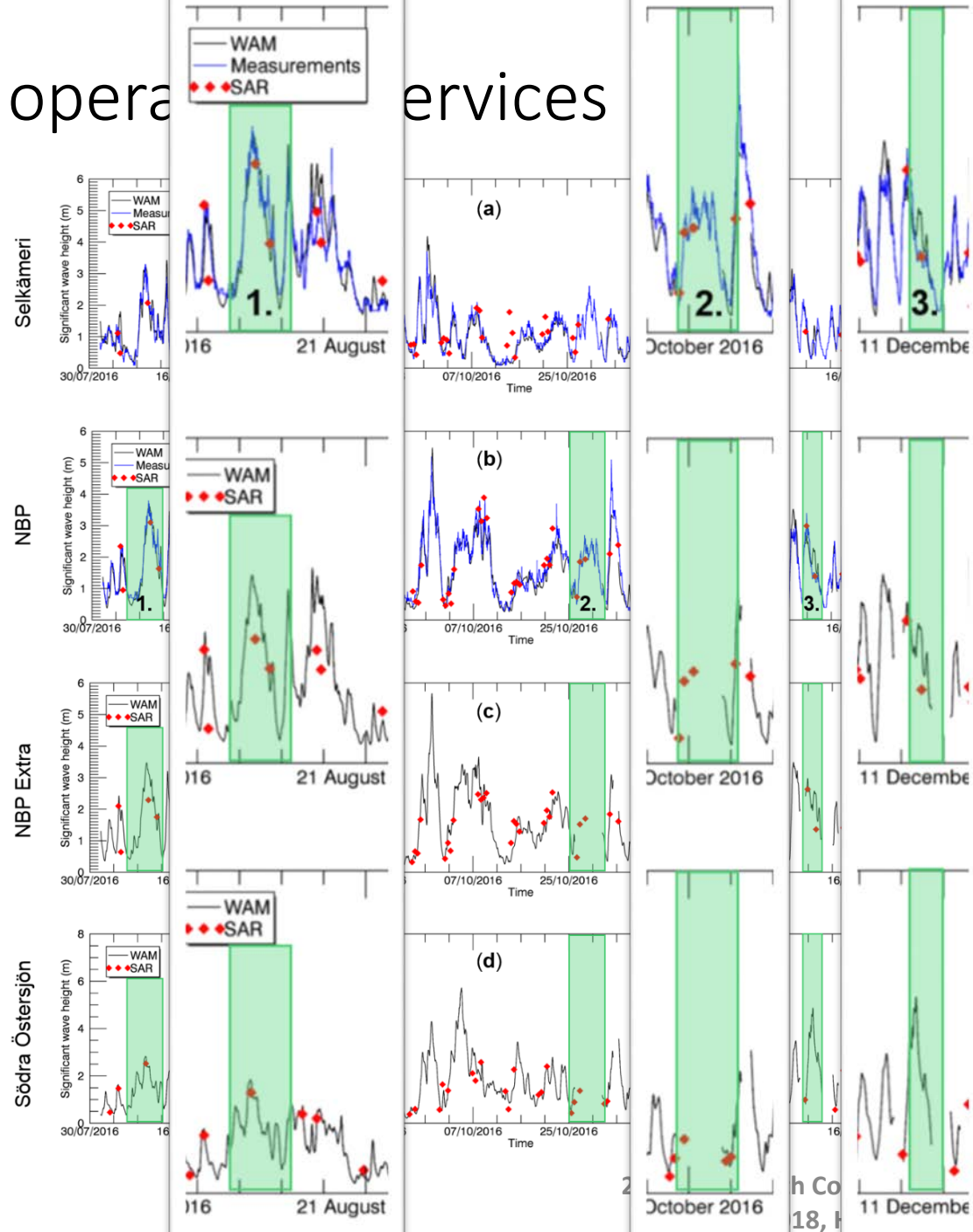
Local variability of sea state from high resolution SAR imagery

- General agreement between SWAN wave model results and SAR-derived H_s values
- Wave height, wavelength and wave propagation direction shows more variability from radar-derived results



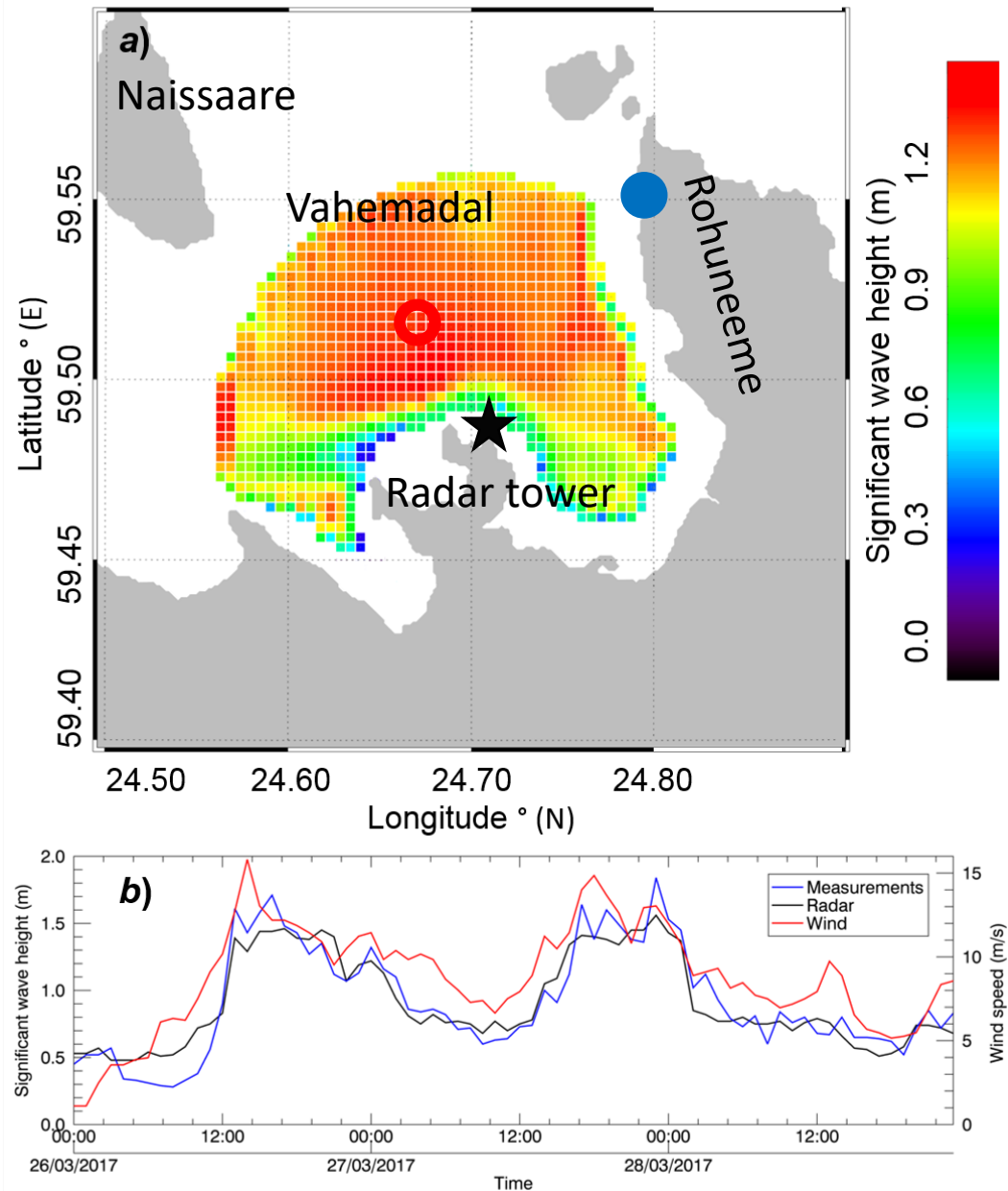
Sentinel-1 data for operational services

- An independent time series from 1st August 2016 until the end of 2016
- Case 1 – mismatch in wave height value on WAM
 - better detailed spatial variability
- Case 3 – similar to Case 1 but with more uniform wave field
- Case 2 – missing *in situ* or model data can be covered by SAR
 - Technical issues
 - Maintenance of measurement device
- Boos measurement station Södra Östersjön – no *in situ* data since 2011, although common high sea



Coastal radar data for operational service

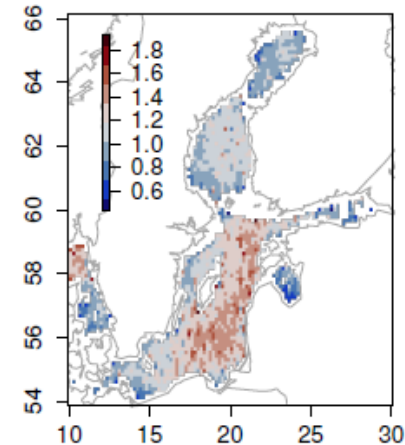
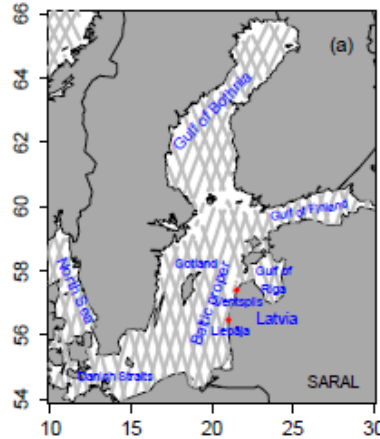
- Average H_S field during 26.03 – 28.03.2017 for NW storm conditions
- Time series of *in situ* measurements and radar-derive H_S show good agreement during the storm
- Similar H_S field has been shown by other authors for comparable conditions
- Waves propagating into Tallinn Bay between the mainland and Naissaare
- Maximum H_S around the tip of the Paljassaare peninsula
 - Depth around 30 m



Statistical mapping of coastal wave field

E.g. Kudryavtseva and Soomere (2017) analysed altimetry data over the Baltic Sea

- Data between 1993-2015
- Output resolution about $0.2 \times 0.1^\circ$

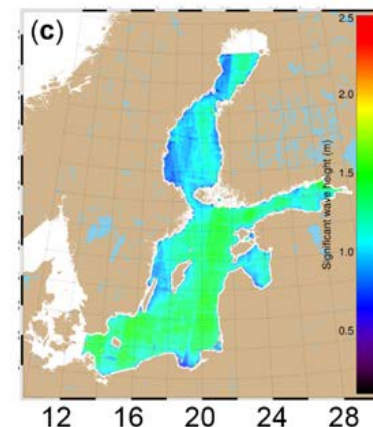
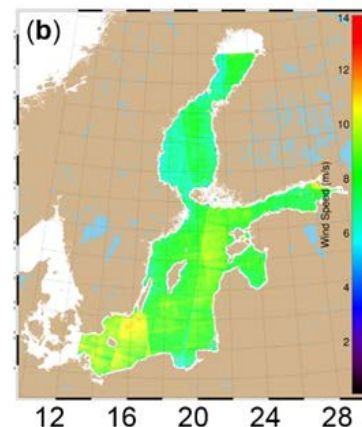
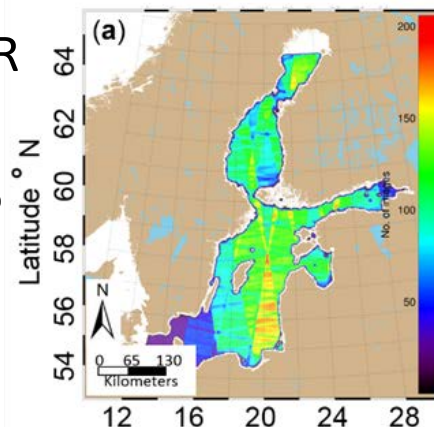


- Similar outcome from SAR data
- Data between 2015-2016
- Output resolution 3 nm (interpolated to 1 nm grid)

No. of images

Average U_{10}

Average H_S



Conclusions

- Methods to estimate total significant wave heights were improved/developed and validated for the Baltic Sea wave climate conditions
 - XWAVE_C for H_S ($r = 0.88$, RMSE = 0.32 m)
 - CWAVE_S1-IW for H_S ($r = 0.88$, RMSE = 0.40 m)
 - Marine radar for H_S ($r = 0.78$, RMSE = 0.23 m)
 - XMOD-2 for U_{10} ($r = 0.90$, RMSE = 2.02 m s⁻¹)
 - CMOD for U_{10} ($r = 0.91$, RMSE = 1.43 m s⁻¹)
- The statistics show that radar-derived results are suitable for routine monitoring of meteo-marine parameters in the Baltic Sea
- SAR-derived values of geophysical parameters are spatially more variable and would provide more detailed wave field compared to wave model
- SAR-derived results could be used for wave model validation
 - Wind data from SAR could be used as wave model forcing

Conclusions

- SAR-derived wave height and wind speed results can replace measurements or wave model results in poorly sampled areas or in cases when data is missing
- SAR enables to observe coastal wave field variations in the Baltic Sea in more detail compare to other EO sensors (altimetry)
- SAR data enable to perform wave climate studies in seasonal and regional scale
- Based on Paljassaare marine radar data analysis wave height can be monitored with high accuracy in space and time
- Considering all above the radar based wind and wave data would be beneficial for maritime situation awareness applications and routine monitoring/forecasting in the Baltic Sea

Thank you for your attention!

